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A proportional-integral-derivative controller (PID controller) is a control loop feedback mechanism (controller) widely used in industrial control systems. A PID

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This paper presents a stochastic, multi-parameters, divergence optimization method for the auto-tuning of proportional integral derivative (PID) controllers

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Cheng- ching yu (author of reactive distillation

Cheng-Ching Yu is the author of Autotuning of PID Controllers (4.00 avg rating, 1 rating, 0 reviews, published 2006), Cheng-Ching Yu s Followers. None yet.

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Recognising the benefits of improved control, this book aims to provide simple and yet effective methods of improving controller performance. It bridges

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